

Tersus BX316 Firmware Version (FW0278) Release

Jun 3, 2019

Overview

Tersus GNSS Inc. ("Tersus") is glad to release the firmware to BX316 OEM board. Firmware version (FW0278) is available for download at www.tersus-gnss.com/pages/software and support documents are available at www.tersus-gnss.com/pages/documents.

Features

- The firmware tracks three constellations: GPS (L1/L2), GLONASS (L1/L2) and BeiDou (B1/B2).
- This firmware provides centimeter-level accurate positioning to meet the wide range of precision positioning applications.
- The 4 GB onboard data storage makes it possible to store raw measurements for post-processing application.
- ➤ The maximum update rate is 20Hz for RTK and 20Hz for raw measurements.
- With a number of configurations, the firmware matches the needs for post-processing workflows, and for the use as a base/rover station or rover.

Change from Previous Versions

Issue	Туре	FW
Increase the number of decimal places for		
latitude and longitude std for log gpgst and log	Bug Fix	FW0278
bestpos.		
Fix a convert GLONASS ephemeris time bug.	Bug Fix	FW0268

Fix the bug of ephemeris log. Fix the SATVIS log. Make the 'rtkcommand reset' work. Optimize the heading code. Baseband fix a Time Quality upgrade without firstly set time possible bug. Switch back AP RTK callback calling order Make synchronous logs have priority over asynchronous Add antenna type field in "thisantenna" log and this information can be converted to RINEX header. Change FSBL Optimize the heading code. Enhancement Fixed the GLONASS string count=0 problem which would cause GLONASS have no observations when the UTC time equals 3 a.m. Expanded the size of RTK ephemeris array. This problem would cause the newly raised GPS satellites not to participate in RTK solution. Fixed the problem of ionospheric model jumping. Added the function of smoothing RTK solution to get POSAVE coordinates. Fixed the bug of RTCM3 encoding and decoding of FW0114 If the input coordinates and actual coordinates differ by more than 30m in one direction, it will stop broadcasting RTCM messages although the		I	
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RTCM logs are input.		
The RTK engine is updated.	Enhancement	
Fixed the bug of solution type in heading log	Bug fix	
Optimized cycle slip detecting method.	Enhancement	FW0089
Fixed the bug of log headingb	Bug fix	FW0087
Optimized heading function.	Bug fix	
Fixed the problem of invalid 'RTKSOURCE' command.	Bug fix	FW0086
Changed new BX316 (serial number start with 022) default storage medium to eMMC.	Enhancement	ment
When input have TAB(it maybe copy from pdf,htmletc.). Make Response enable.	Enhancement	
The RTCM date will be broadcast only when the coordinates are fixed.	Bug fix	
Changed the RTCM1230 encoding and RTCM1033 decoding.	Bug fix	
AP added more checks for response.	Enhancement	
Make file downloads more robust.	Enhancement	
Fixed the bug of Galileo and BeiDou sig mask and GPS and GLONASS sig mask.	Bug fix	FW0082
Add DAC control clock drift range protection to +/- 0.6 ppm	Enhancement	
Consider clock drift error at recover clock drift stage.	Enhancement	
Expand clock drift recover range to 15Hz and expand clock drift tuning range to 40Hz.	Enhancement	
The RTK engine is updated to version 3.0 which is more stable re reliable.	Enhancement	FW0041
The maximum update rate is 20Hz for RTK.	Enhancement	

Add RTCMv3 messages, including GPS ephemeris (MT1019), GLONASS ephemeris (MT1020), BDS ephemeris (MT1042), GLONASS bias information (MT1230).	Enhancement	
Optimizing the upgrade program. Even if the OEM board is unable to boot, the upgrade program may be enforced.	Enhancement	
The logic of firmware update has been optimized.	Enhancement	
The USB feature of firmware has been optimized.	Enhancement	
Fixed the bug when the updating is not successful.	Bug fix	
Changed the naming method of storage files. The time when the file was created is taken as the file name.	Enhancement	
Added a new feature of [base network]. (refer to < User Manual For BX Series GNSS Receiver >, 2.6.1)	Enhancement	